



Mathematical Statistics
Stockholm University

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Research Report 2010:3

ISSN 1650-0377

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Random networks with preferential growth and vertex death in continuous time

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January 2010

Abstract

A dynamic model for a random network evolving in continuous time is defined where new vertices are born and existing vertices may die. The fitness of a vertex is defined as the total number of connections that the vertex has held, that is, its accumulated degree. A new vertex is then connected to an existing vertex with probability proportional to a function b of the fitness of the existing vertex, and a vertex dies at a rate given by a function d of its fitness. Using results from the theory of general branching processes, an expression for the asymptotic empirical fitness distribution $\{p_k\}$ is derived and analyzed for a number of specific choices of b and d . When $b(i) = i + \alpha$ and $d(i) = \beta$ – that is, linear preferential attachment for the newborn and random deaths – then $p_k \sim k^{-(2\alpha+1)}$. When $b(i) = i + 1$ and $d(i) = \beta(i + 1)$, with $\beta < 1$, then $p_k \sim (1 + \beta)^{-k}$, that is, if also the death rate is proportional to the fitness, then the power law distribution is lost. Furthermore, when $b(i) = i + 1$ and $d(i) = \beta(i + 1)^\gamma$, with $\beta, \gamma < 1$, then $\log p_k \sim -k^\gamma$ – a stretched exponential distribution.

Keywords: Branching process, random network, preferential attachment, degree distribution, power law distribution.

AMS 2000 Subject Classification: 60J85, 90B15, 05C80.

1 Introduction

Empirical studies on real networks has revealed that many of them exhibit features that are not captured by the classical Erdős-Rényi graph. In particular, many networks tend to have a quite heavy tailed degree distribution, often described by a power law, that is, the fraction of vertices with degree k decays as $k^{-\tau}$ for some exponent τ . To capture this, a number of new graph

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models have been developed that allow for this type of degree distribution; see for instance the seminal paper by Bollobás et al. [6] (the setup described there includes many previously studied models as special cases) and the references therein.

A model type that has received a lot of attention is based on preferential attachment: new vertices are successively added to the network and are connected to existing vertices proportionally to a function $f(k) = k^\gamma$ of the degree. The mechanism was introduced in the context of network modeling by Barabási and Albert [3], who observed that, for $\gamma = 1$ – that is, linear preferential attachment – it seemed to lead to power law distributions with exponent $\tau = 3$ for the degrees. This was proved rigorously in Bollobás et al. [5]. Krapivsky and Redner [17] later derived heuristic results indicating that the regimes $\gamma \leq 1$ and $\gamma > 1$ are qualitatively different: for $\gamma > 1$ the degree distribution is degenerate in the sense that there is a single dominant vertex that is connected to almost every other vertex. This has been confirmed by Oliveira and Spencer [22]. Recently Dereich and Mörters [11] has studied the evolution in the sublinear regime $\gamma < 1$, where indeed there is a non-trivial limiting degree distribution, in greater detail.

Most preferential attachment models in the literature are defined in discrete time. Rudas and Toth [23] however studies the model from a new perspective, embedding it in continuous time and interpreting it as a continuous time branching process. This opens up for the use of well established results from the theory of branching processes. For instance, an expression for the almost sure limit of the empirical degree sequence is obtained. Compared to the traditional techniques for analyzing models with linear preferential attachment, the approach has the advantage that it applies for any $\gamma \leq 1$. We mention also the paper by Athreya et al. [2], where the linear case $\gamma = 1$ is studied by aid of a different type of branching process embedding.

The purpose of the current paper is to define and analyze a preferential attachment model in continuous time where vertices are not just added but may also die, and where the death rate of a vertex is taken to be a function of its previous success, quantified by its accumulated degree. Using results from the theory of general branching processes, a characterization of the asymptotic distribution of the accumulated degrees is derived and analyzed in various special cases. This generalizes results from [23]. We mention also the paper [4] by Britton and Lindholm, where a model is treated that is similar in spirit but not based on preferential attachment.

Preferential attachment models incorporating deaths of vertices are much less studied than pure growth models, while real networks may well be affected by vertex emigration. Existing rigorous results are restricted to the case when vertices die randomly, that is, the death mechanism does not depend on features of the vertices (age, degree etc); see Cooper et al. [9] and Chung and Lu [7]. See also Moore et al. [19] and Deo and Cami [10] for heuristic results, the latter concerning a situation where vertices die with a probability inversely

proportional to their degree (note however that our model is not directly comparable to these models, since it evolves in continuous time). Concentration results are so far quite weak, see e.g. [9, Lemma 4.1], and do not exist for models with more complicated death mechanisms.

1.1 Definition of the model

We now proceed to define the model. As already described, a vertex population evolving in continuous time is considered where existing vertices give birth to new vertices but may also die. More specifically, a vertex that is alive at time t and that has given birth to i new vertices during its life time, gives birth to an $i + 1$:st vertex at rate $b(i)$, that is, the probability that the vertex gives birth in the time interval $(t, t + \varepsilon)$ is $b(i)\varepsilon + o(\varepsilon)$. Furthermore, the vertex dies at rate $d(i)$, that is, its probability of dying during $(t, t + \varepsilon)$ is $d(i)\varepsilon + o(\varepsilon)$. Let ξ be a random point process on $[0, \infty)$ with points (representing the births) generated according to the above rules. Starting from a single root vertex at time 0, each vertex x reproduces according to an independent copy ξ_x of ξ . This means that the vertex population evolves as a birth and death process in continuous time and hence fits into the framework of general branching processes; see e.g. Jagers [15, Chapter 6]. Below we shall formulate conditions that guarantee that the process is supercritical, so that the vertex population grows to infinity with positive probability.

Write \mathcal{Z}_t for the set of vertices that are alive at time t , and, for $x \in \mathcal{Z}_t$, let A_t^x denote the total number of children that vertex x has produced up to time t (including children that are no longer alive), also referred to as the *fitness* of the vertex. The time until the next birth in the population is exponentially distributed with parameter $\sum_{x \in \mathcal{Z}_t} b(A_t^x)$ and the time until the next death is exponentially distributed with parameter $\sum_{x \in \mathcal{Z}_t} d(A_t^x)$. Hence the probability that the next event that occurs in the population is a birth is given by

$$\frac{\sum_{x \in \mathcal{Z}_t} b(A_t^x)}{\sum_{x \in \mathcal{Z}_t} (b(A_t^x) + d(A_t^x))}. \quad (1)$$

and the probability that the birth occurs at vertex x is proportional to $b(A_t^x)$. We shall see later that, under certain assumption on b and d , the ratio (1) converges to a number in $(0, 1)$.

The vertex population described above naturally gives rise to a network structure: directed edges are created between a vertex and its children, pointing from the child to the mother. When a vertex dies it turns into a *ghost* and all edges associated with it are turned into *ghost links*. According to the dynamics, the rate at which a vertex produces/attracts new vertices depends on its previous success, measured by its in-degree, including ghost links. Whether or not it is realistic to include the ghost links depends on the setting. In many situations it is indeed natural to assume that a vertex benefits from its total historical success rather than just the contributions generated by vertices that

are still present in the network (think e.g. of coauthor-ship networks, recruitment networks etc). A model where ghost links are excluded in the definition of the fitness can be analyzed by the same means as the present model. The calculations however become cumbersome and do not lead to explicit expressions.

1.2 Results

Let $\rho(t)$ be the density of ξ , that is,

$$\rho(t) = \varepsilon^{-1} \mathbb{P}((t, t + \varepsilon) \text{ contains a point from } \xi)$$

and define the Laplace transform

$$\hat{\rho}(\lambda) = \int_0^\infty e^{-\lambda t} \rho(t) dt. \quad (2)$$

Clearly $\hat{\rho}(\lambda)$ increases as $\lambda \rightarrow 0$, and we write

$$\underline{\lambda} = \inf\{\lambda > 0 : \hat{\rho}(\lambda) < \infty\}. \quad (3)$$

Our first result is an expression for $\hat{\rho}(\lambda)$.

Proposition 1.1 *We have that*

$$\hat{\rho}(\lambda) = \sum_{k=0}^{\infty} \prod_{i=0}^k \frac{b(i)}{\lambda + b(i) + d(i)}.$$

Throughout, we shall assume that the functions b and d are such that

$$\hat{\rho}(\lambda^*) = 1 \quad \text{has a solution } \lambda^* \in (0, \infty). \quad (C.1)$$

In fact, we shall assume that

$$\lambda^* > \underline{\lambda}. \quad (C.2)$$

It is well-known from the theory of branching processes that, when $\underline{\lambda} < \infty$, the condition (C.1) is equivalent to the process being supercritical. To be more precise, write $\xi(t)$ for the ξ -measure of $[0, t]$ and let $Z_t = |\mathcal{Z}_t|$ be the number of vertices alive at time t . Then $\mathbb{P}(Z_t \rightarrow \infty) > 0$ if and only if $\mathbb{E}[\xi(\infty)] > 1$ if and only if $\lambda^* > 0$; see [15, Chapter 6]. Writing

$$\hat{\rho}(\lambda) = \sum_{i=0}^{\infty} e^{-\sum_{i=0}^k \log\left(1 + \frac{\lambda + b(i)}{\lambda + b(i) + d(i)}\right)} \quad (4)$$

reveals that a necessary condition for having $\underline{\lambda} < \infty$ (which is indeed necessary for (C.1)) is that

$$\sum_{i=0}^{\infty} \frac{1 + d(i)}{b(i) + d(i)} = \infty.$$

Furthermore, a sufficient condition for having $\hat{\rho}(\lambda) < \infty$ for all $\lambda > 0$ (so that $\underline{\lambda} = 0$) is that

$$\frac{1 + d(i)}{d(i) + b(i)} \geq ci^{-\gamma} \quad \text{for some } \gamma > 1. \quad (5)$$

Indeed, then the exponent in (4) grows at least like $k^{-\gamma+1}$, making the sum convergent. Also note that (C.1) – or, more specifically, the fact that $\underline{\lambda} < \infty$ – guarantees that the process does not explode in finite time: a sufficient condition for non-explosion is that $\mathbb{E}[\xi(t)] < \infty$ for some $t > 0$, see [15, Theorem 6.2.2], and, since $\rho(t)dt = \mathbb{E}[\xi(dt)]$, it is clear that $\underline{\lambda}$ cannot be finite if this does not hold.

We are now ready to formulate the main theorem, which is a characterization of the asymptotic fitness distribution in the vertex population. To this end, recall that Z_t is the number of alive vertices at time t and write Z_t^k for the number of alive vertices at time t with fitness k . Furthermore, let L be a random variable distributed as the life time of a vertex.

Theorem 1.1 *Assume that b and d satisfy conditions (C.1) and (C.2). Then, for all k , on the event $\{Z_t \rightarrow \infty\}$, almost surely*

$$\lim_{t \rightarrow \infty} \frac{Z_t^k}{Z_t} = \frac{C}{\lambda^* + b(k) + d(k)} \prod_{i=0}^{k-1} \frac{b(i)}{\lambda^* + b(i) + d(i)}$$

where $C^{-1} = \int_0^\infty e^{-\lambda^* t} \mathbb{P}(L > t) dt$ and the empty product arising for $i = 0, 1$ is defined as 1.

The rest of the paper is organized as follows. In Section 2 we state the results we shall need from the theory of branching process and, in Section 3, Proposition 1.1 and Theorem 1.1 are proved. Then, in Section 4, the limiting distribution in Theorem 1.1 is analyzed in more detail for a number of specific choices of $b(i)$ and $d(i)$. Finally, some possibilities for further work are mentioned in Section 5.

2 Preliminaries on branching processes

The corpus of literature on branching processes is vast and we do not intend to give a survey; for this, see Jagers [15] or the more expository book by Haccou et al. [13]. We shall however briefly explain the concepts that are needed to establish Theorem 1.1. These revolve around general branching processes counted with random characteristics. In a general branching process, the individuals reproduce independently of each other according to a random point process ξ on $[0, \infty)$ during a life-time L , where there are no restrictions on the dependence structure between ξ and L . An individual x can be represented

as $x = (j_1, \dots, j_n)$ indicating that x is the j_n :th child of the j_{n-1} :th child ... of the j_1 :th child of the ancestor. Hence the space of possible individuals is

$$\Omega = \bigcup_{i=0}^{\infty} \mathbb{N}^n.$$

Write σ_x for the time when the individual x is born, that is, $\sigma_0 = 0$ and, if x is the i :th child of the individual x' , then $\sigma_x = \sigma_{x'} + \inf\{t : \xi_{x'}(t) \geq i\}$.

Roughly, when counting a branching processes with a random characteristic, a random score is assigned to each individual and the quantity of interest is then the total score in the population. More specifically, let $\phi(t)$ be a real-valued stochastic process with $\phi(t) = 0$ for $t \leq 0$ giving the score of an individual of age t . The score of the individual x at time t is then given by $\phi_x(t) = \phi(t - \sigma_x)$ and the total score in the population at time t becomes

$$Z_t^\phi = \sum_{x \in \Omega} \phi_x(t).$$

Examples of common characteristics are $\phi(t) = \mathbf{1}\{t \leq 0\}$, in which case Z_t^ϕ is the number of individuals born up to time t , and $\phi(t) = \mathbf{1}\{0 \leq t < L\}$, in which case Z_t^ϕ is the number of individuals that are alive at time t – this quantity we shall simply use the notation Z_t for. These characteristics are both individual, meaning that ξ_x depends only on the process of descendants of x . Characteristics that involve information also about preceding generations are called relational. An example of such a characteristic that will turn up later is when an individual is assigned the value 1 if its mother is still alive and 0 otherwise.

The Laplace transform $\hat{\rho}(\lambda)$ of the density $\rho(t)$ of ξ and the related quantity $\underline{\lambda}$ are defined as in (2) and (3). The solution λ^* to the equation $\hat{\rho}(\lambda) = 1$ is called the Malthusian parameter and the process is subcritical, critical or supercritical depending on whether $\lambda^* < 0$, $= 0$ or > 0 . A more frequent formulation of the definition of λ^* in the literature is as the solution to the equation

$$\int_0^\infty e^{-\lambda t} \mathbb{E}[\xi(dt)] = 1,$$

where, as in Section 1.1, $\xi(t) = \xi([0, t])$. Since $\mathbb{E}[\xi(dt)] = \rho(t)dt$, the formulations are clearly equivalent.

Now, Theorem 1.1 will turn out to be a direct consequence of the following result concerning almost sure convergence of ratios of random characteristics.

Theorem 2.1 (Nerman (1984)) *Consider a supercritical branching process with Malthusian parameter $\lambda^* > \underline{\lambda}$ and let ϕ and ψ be two individual characteristics satisfying*

$$\mathbb{E}[\sup_t \{e^{-\lambda t} \phi(t)\}] < \infty \quad \text{for some } \lambda < \lambda^* \quad (6)$$

and likewise for ψ . Then, on the event $\{Z_t \rightarrow \infty\}$, almost surely

$$\frac{Z_t^\phi}{Z_t^\psi} \rightarrow \frac{\hat{\phi}(\lambda^*)}{\hat{\psi}(\lambda^*)}$$

where $\hat{\phi}(\lambda) = \int_0^\infty e^{-\lambda t} \mathbb{E}[\phi(t)] dt$.

Remark 1. The characteristics we shall work with will in general be bounded and, for such characteristics, (6) is trivially satisfied.

Remark 2. As pointed out in [13, pp 163], the conclusion of the theorem holds true also for relational characteristics provided that these depend only on a finite number of preceding generations; see Jagers and Nerman [16] for details.

3 Proofs

We now return to the specific setting defined in Section 1.1, where ξ is the point process generated by the described birth and death rules.

Proof of Proposition 1.1. The expression for $\hat{\rho}(\lambda)$ follows from straightforward calculations. First note that

$$\hat{\rho}(\lambda) = \sum_{k=0}^{\infty} b(k) \int_0^{\infty} e^{-\lambda t} \mathbb{P}(\xi(t) = k \cap L > t) dt,$$

where trivially

$$\mathbb{P}(\xi(t) = k \cap L > t) = \mathbb{P}(\xi(t) = k) - \mathbb{P}(\xi(t) = k \cap L \leq t).$$

Consider a generic vertex (the root vertex for instance) and write T_i for the time, counting from the birth of the vertex, when its i :th child is born, with $T_i := \infty$ if $\xi(\infty) < i$. Also, when $T_i < \infty$, define $\Delta_i^b = T_{i+1} - T_i$ and let Δ_i^d be the time, counting from T_i , until the vertex dies. For $k = 0$, we obtain

$$\begin{aligned} \int_0^{\infty} e^{-\lambda t} \mathbb{P}(\xi(t) = 0 \cap L > t) dt &= \int_0^{\infty} e^{-(\lambda + b(0) + d(0))t} dt \\ &= \frac{1}{\lambda + b(0) + d(0)}, \end{aligned}$$

where $e^{-(b(0) + d(0))t}$ is the probability that nothing happens in the process up to time t . To deal with $k \geq 1$, note that

$$\mathbb{P}(\xi(t) = k) = \mathbb{P}(\xi(t) = k | T_k < \infty) \mathbb{P}(T_k < \infty),$$

with

$$\begin{aligned} \mathbb{P}(\xi(t) = k | T_k < \infty) &= \mathbb{P}(\xi(t) \geq k | T_k < \infty) \\ &\quad - \mathbb{P}(\xi(t) \geq k + 1 | T_{k+1} < \infty) \mathbb{P}(T_{k+1} < \infty | T_k < \infty). \end{aligned}$$

Here

$$\mathbb{P}(\xi(t) \geq k | T_k < \infty) = \mathbb{P}\left(\sum_{i=0}^{k-1} \Delta_i^b \leq t | T_k < \infty\right),$$

where, conditionally on $T_k < \infty$, the variables $\Delta_0^b, \dots, \Delta_{k-1}^b$ are independent and Δ_i^b is exponentially distributed with parameter $b(i) + d(i)$. Similarly,

$$\begin{aligned} \mathbb{P}(\xi(t) = k \cap L \leq t) &= \mathbb{P}(\xi(t) = k \cap L \leq t | T_k < \infty \cap T_{k+1} = \infty) \cdot \\ &\quad \mathbb{P}(T_k < \infty \cap T_{k+1} = \infty) \end{aligned}$$

with

$$\mathbb{P}(\xi(t) = k \cap L \leq t | T_k < \infty \cap T_{k+1} = \infty) = \mathbb{P}\left(\sum_{i=0}^{k-1} \Delta_i^b + \Delta_i^d \leq t | T_k < \infty \cap T_{k+1} = \infty\right),$$

where, conditionally on $T_k < \infty \cap T_{k+1} = \infty$, the variables $\Delta_1^b, \dots, \Delta_{k-1}^b, \Delta_k^d$ are independent, Δ_i^b exponentially distributed with parameter $b(i) + d(i)$ and Δ_k^d exponentially distributed with parameter $b(k) + d(k)$. Also note that

$$\begin{aligned} \mathbb{P}(T_k < \infty) &= \prod_{i=0}^{k-1} \frac{b(i)}{b(i) + d(i)} =: q_k \\ \mathbb{P}(T_{k+1} < \infty | T_k < \infty) &= \frac{b(k)}{b(k) + d(k)} =: q'_k \\ \mathbb{P}(T_k < \infty \cap T_{k+1} = \infty) &= \frac{d(k)}{b(k) + d(k)} \prod_{i=0}^{k-1} \frac{b(i)}{b(i) + d(i)} =: q''_k. \end{aligned}$$

For independent exponential variables $\{X_i\}$, where X_i has parameter $b(i) + d(i)$, write

$$I_k = \int_0^\infty e^{-\lambda t} \mathbb{P}(X_0 + \dots + X_{k-1} \leq t) dt.$$

Combining all of the above, we get that

$$\hat{\rho}(\lambda) = \frac{b(0)}{b(0) + d(0)} + \sum_{k=1}^{\infty} b(k) \left(q_k I_k - (q_k q'_k + q''_k) I_{k+1} \right), \quad (7)$$

and all that remains is to note that,

$$\begin{aligned} I_k &= \frac{1}{\lambda} \int_0^\infty e^{-\lambda t} f_{X_0 + \dots + X_{k-1}}(t) dt \\ &= \frac{1}{\lambda} \prod_{i=0}^{k-1} \frac{b(i) + d(i)}{\lambda + b(i) + d(i)}, \end{aligned}$$

where the first equality follows from partial integration and the second from independence. Substituting this, and the expressions for q_k , q'_k and q''_k , into (7) gives the desired formula for $\hat{\rho}(\lambda)$. \square

We proceed to prove the main result, Theorem 1.1, which, as already mentioned, follows from Theorem 2.1.

Proof of Theorem 1.1. Consider the characteristic

$$\phi(t) = \mathbf{1}\{\xi(t) = k \cap 0 < t < L\},$$

that is, $Z_t^\phi = Z_t^k$ is the number of alive vertices with k children at time t , and let $\psi(t) = \mathbf{1}\{0 < t < L\}$ so that $Z_t^\psi = Z_t$ is the number of alive vertices at time t . These characteristics are both bounded, and hence, since b and d are assumed to be such that (C.1) and (C.2) are satisfied, all assumptions of Theorem 2.1 are fulfilled. It follows that, on the event $Z_t \rightarrow \infty$, the ratio Z_t^k/Z_t converges almost surely to the limit identified in Theorem 2.1. The expression in the nominator becomes

$$\hat{\phi}(\lambda^*) = \int_0^\infty e^{-\lambda^*t} \mathbb{P}(\xi(t) = k \cap L > t) dt,$$

and identical calculations as in the proof of Proposition 1.1 yields the formula in Theorem 1.1. \square

4 Examples

We now investigate the behavior of the limiting fitness distribution in Theorem 1.1 for a few specific choices of birth and death rates b and d . The limiting distribution is henceforth denoted by $\{p_k\}$.

Example 1. First consider the case when $b(i) = i + \alpha$ and $d(i) = \beta$ with $\alpha > 0$, that is, the birth rate is a linear function of the fitness and the vertices die at a constant rate. This means that a new vertex is connected to an existing vertex with a probability that depends linearly on the fitness of the existing vertex, and the vertices die at random. Using the relation

$$\prod_{i=0}^k (i + c) = \frac{\Gamma(k + 1 + c)}{\Gamma(c)},$$

we get that

$$\hat{\rho}(\lambda) = \sum_{k=0}^{\infty} \prod_{i=0}^k \frac{i + \alpha}{\lambda + i + \alpha + \beta} = \frac{\Gamma(\lambda + \alpha + \beta)}{\Gamma(\alpha)} \sum_{k=0}^{\infty} \frac{\Gamma(k + 1 + \alpha)}{\Gamma(k + 1 + \alpha + \beta + \lambda)}.$$

Van der Hofstad et al. [14, Lemma 5.4] derives the formula

$$\sum_{k=0}^n \frac{\Gamma(k + a)}{\Gamma(k + c)} = \frac{1}{1 + a - c} \left(\frac{\Gamma(n + 1 + a)}{\Gamma(n + c)} - \frac{\Gamma(a)}{\Gamma(c - 1)} \right), \quad (8)$$

and, by Stirlings formula, $\Gamma(k+c)/\Gamma(k) \sim k^c$ as $k \rightarrow \infty$. It follows that

$$\hat{\rho}(\lambda) = \begin{cases} \infty & \text{if } \lambda \leq 1 - \beta; \\ \frac{\alpha}{\lambda + \beta - 1} & \text{otherwise.} \end{cases}$$

Hence $\lambda^* = 1 + \alpha - \beta$, implying that the process is supercritical if $\beta < \alpha + 1$. For the fitness distribution we get that

$$p_k = \frac{C}{k+1+2\alpha} \prod_{i=0}^{k-1} \frac{i+\alpha}{i+1+2\alpha} = C' \frac{\Gamma(k+\alpha)}{\Gamma(k+2+2\alpha)} \sim k^{-(2\alpha+1)}.$$

The limiting behavior of the fitness distribution is hence unaffected by the vertex death. This is explained by the fact that the vertices die randomly, that is, given that the next thing to occur is a vertex death, the vertex to die is chosen uniformly at random, and such a mechanism does not affect the tail behavior of the power law distribution generated by the birth mechanism. With $\alpha = 1$ the expression for p_k is in agreement with previous results for pure linear preferential attachment.

Recall that, given the development of the process up to time t , the probability that the next thing occurring is a vertex birth is given by (1), where A_t^x is the fitness of vertex x at time t . If the characteristics given by $\phi_x(t) = b(A_{t-\sigma_x}^x)$ and $\psi_x(t) = d(A_{t-\sigma_x}^x)$ satisfy the condition (6), then it follows from Theorem 2.1 that the probability converges almost surely to a number in $(0, 1)$. This number is in general difficult to determine, but in the current case, denoting the total fitness $A_t^{tot} = \sum_{x \in Z_t} A_t^x$, we get

$$\frac{\sum_{x \in Z_t} b(A_t^x)}{\sum_{x \in Z_t} (b(A_t^x) + d(A_t^x))} = \frac{A_t^{tot} + \alpha Z_t}{A_t^{tot} + (\alpha + \beta) Z_t}.$$

The total fitness in the alive population can be obtained by counting the population by the characteristic $\psi(t) = \mathbf{1}\{t > 0 \text{ and the mother of the individual is alive}\}$. Hence, by Theorem 2.1 and the second remark following it, the ratio A_t^{tot}/Z_t converges to 1 almost surely and it follows that

$$\lim_{t \rightarrow \infty} \mathbb{P}(\text{the next event is a vertex death}) = \frac{1 + \alpha}{1 + \alpha + \beta}.$$

This probability is strictly larger than $1/2$ precisely when $\beta < \alpha + 1$, that is, when the process is supercritical.

Example 2. Next consider the case when $b(i) = i + 1$ and $d(i) = \beta(i + 1)$, that is, both the birth and the death rate are linear functions of the fitness.

In this case, by (5), we have $\hat{\rho}(\lambda) < \infty$ for all $\lambda > 0$, and it is given by

$$\begin{aligned}\hat{\rho}(\lambda) &= \sum_{k=0}^{\infty} \prod_{i=0}^k \frac{i+1}{\lambda + (1+\beta)i + (1+\beta)} \\ &= \Gamma\left(\frac{\lambda+1+\beta}{1+\beta}\right) \sum_{k=0}^{\infty} \frac{\Gamma(k+2)}{\Gamma\left(k+1+\frac{\lambda+1+\beta}{1+\beta}\right)} \frac{1}{(1+\beta)^k} \\ &= F\left(1, 1, \frac{\lambda+1+\beta}{1+\beta}, \frac{1}{1+\beta}\right) - 1,\end{aligned}$$

where F denotes Gauss hypergeometric function; see Abramowitz and Stegun [1, Chapter 15]. The equation $\hat{\rho}(\lambda^*) = 1$ cannot be solved explicitly but a numerical solution is easily obtained for a given value of β . The process is supercritical precisely when $\beta < 1$, since the expected number of children produced by a vertex is given by

$$\mathbb{E}[\xi(\infty)] = \sum_{k=1}^{\infty} \mathbb{P}(\xi(\infty) \geq k) = \sum_{k=1}^{\infty} \prod_{i=0}^{k-1} \frac{b(i)}{b(i)+d(i)} = \sum_{k=1}^{\infty} \frac{1}{(1+\beta)^k} = \frac{1}{\beta}. \quad (9)$$

The asymptotic fitness distribution is

$$\begin{aligned}p_k &= \frac{C}{\lambda^* + (1+\beta)(k+1)} \prod_{i=0}^{k-1} \frac{i+1}{\lambda^* + (1+\beta)(i+1)} \\ &= C' \frac{\Gamma(k+1)}{\Gamma\left(k+3+\frac{\lambda^*}{1+\beta}\right)} \frac{1}{(1+\beta)^k} \\ &\sim k^{-(2+\frac{\lambda^*}{1+\beta})} \frac{1}{(1+\beta)^k}.\end{aligned}$$

A mechanism where the vertices die at a rate proportional to their fitness hence destroys the power law distribution obtained without vertex deaths regardless of how small the proportionality constant is and instead produces a (super)exponentially decaying fitness distribution.

We remark that $b(i) = (i+1)^\gamma$ and $d(i) = \beta(i+1)^\gamma$ gives rise to the same exponential decay for any $\gamma > 0$. Indeed,

$$\begin{aligned}p_k &= \frac{1}{\lambda^* + (1+\beta)(k+1)^\gamma} \prod_{i=0}^{k-1} \frac{(i+1)^\gamma}{\lambda^* + (1+\beta)(i+1)^\gamma} \\ &\sim \frac{1}{(1+\beta)^k} e^{-\sum_{i=0}^{k-1} \log\left(1+\frac{\lambda^*}{(1+\beta)(i+1)^\gamma}\right)},\end{aligned}$$

where the sum in the exponent grows like $k^{1-\gamma}$ for $\gamma < 1$ and is convergent for $\gamma > 1$.

Example 3. Next take $b(i) = i+1$ and $d(i) = \beta(i+1)^\eta$ for $\beta < 1$ and $\eta \in (0, 1)$. Also in this case $\hat{\rho}(\lambda) < \infty$ for all λ and, by comparison with the

previous example, $\beta < 1$ guarantees that the process is supercritical. For the fitness distribution we get that

$$\log p_k \sim -\sum_{i=0}^k \log \left(1 + \frac{\lambda^* + \beta(i+1)^\eta}{i+1} \right) \sim -k^\eta,$$

that is, $p_k \sim e^{-k^\eta}$. Vertex deaths determined by a sublinear function of the fitness hence also destroy the power law distribution obtained without vertex death, bringing it down to a stretched exponential distribution. In contrast to the case when the vertices die at random however, the tail behavior of the distribution is changed by the vertex deaths.

Again we remark that $b(i) = (i+1)^\gamma$ and $d(i) = \beta(i+1)^\eta$ for arbitrary $\gamma > \eta > 0$ with $\gamma - \eta \in (0, 1)$ gives rise to the same type of fitness distribution: a similar derivation as above implies that $\log p_k \sim -k^{1+\eta-\gamma}$.

Example 4. Finally, consider a situation with $b(i) = \alpha$ and $d(i) = (i+1)^{-1}$, that is, new vertices attach randomly to existing vertices and vertex deaths occur inversely proportional to the fitness. Analogously to (9) we get that

$$\mathbb{E}[\xi(\infty)] = \Gamma \left(1 + \frac{1}{\alpha} \right) \sum_{k=1}^{\infty} \frac{\Gamma(k+1)}{\Gamma \left(1 + \frac{1}{\alpha} \right)},$$

and using (8) it follows that

$$\mathbb{E}[\xi(\infty)] = \begin{cases} \infty & \text{if } \alpha \geq 1; \\ \frac{\alpha}{1-\alpha} & \text{otherwise.} \end{cases}$$

Hence the process is supercritical if and only if $\alpha > 1/2$. The Laplace transform is

$$\begin{aligned} \hat{\rho}(\lambda) &= \sum_{i=0}^{\infty} \left(\frac{\alpha}{\lambda + \alpha} \right)^{k+1} \frac{\Gamma(k+2)}{\Gamma \left(k+2 + \frac{1}{\lambda+\alpha} \right)} \\ &= F \left(1, 1, 1 + \frac{1}{\lambda + \alpha}, \frac{\alpha}{\lambda + \alpha} \right) - 1, \end{aligned}$$

where again F is the hypergeometric function, and the equation $\hat{\rho}(\lambda^*) = 1$ is easily solved numerically for a given value of α . As for the fitness distribution, we have

$$\begin{aligned} p_k &= \frac{1}{\lambda^* + \alpha + \frac{1}{k+1}} \prod_{i=0}^{k-1} \frac{\alpha}{\lambda^* + \alpha + \frac{1}{k+1}} \\ &= \frac{1}{\alpha} \left(\frac{\alpha}{\lambda^* + \alpha} \right)^{k+1} \frac{\Gamma(k+2)}{\Gamma \left(k+2 + \frac{1}{\lambda^* + \alpha} \right)} \\ &\sim \left(\frac{\alpha}{\lambda^* + \alpha} \right)^k k^{-\frac{1}{\lambda^* + \alpha}}, \end{aligned}$$

that is, the fitness distribution decays (super)exponentially at rate $\alpha/(\lambda^* + \alpha)$. The fact that vertices that are not successful in acquiring edges dies at a higher rate is hence not sufficient in itself to explain the power law distributions for the fitnesses.

5 Concluding remarks

A basic question in the theory of branching processes concerns the growth rate of the population in the case of non-extinction. Under mild conditions on the reproduction process, the growth is exponential with a rate determined by the Malthusian parameter λ^* . More precisely

$$e^{\lambda^* t} Z_t \rightarrow cX \quad \text{almost surely as } t \rightarrow \infty,$$

where X is a proper random variable. A necessary and sufficient condition for X to be almost surely positive is the classical $x \log x$ -condition. With $\tilde{\xi}(\lambda) = \int_0^\infty e^{-\lambda t} \xi(dt)$, it reads:

$$\mathbb{E}[\tilde{\xi}(\lambda^*) \log^+ \tilde{\xi}(\lambda^*)] < \infty.$$

We shall not attempt to derive conditions for this in terms of $b(i)$ and $d(i)$ here.

There are a number of questions about the studied model that deserve further investigation. What about the global properties of the obtained structure for instance? If the ghost links are included one gets a random tree, analyzed in Rudas and Toth [23], and excluding the ghost links gives rise to a forest. Will there be an infinite component in this forest? How does the answer depend on $b(i)$ and $d(i)$? Another issue to look into is the time evolution of the process. For models without vertex death it is known that the maximal degree grows polynomially of the same order as the first vertex; see Móri [20]. Is this the case also in the current setting for the maximal fitness? Recently Dehrich and Mörters [11] has shown for a model with attachment function k^γ and no vertex death that there is a phase transition at $\gamma = 1/2$: if $\gamma > 1/2$ there is a persistent hub that will be of maximal degree at all but at most finitely many times, while, if $\gamma < 1/2$, there is no persistent hub. Is there a similar phenomenon in a model with vertex death?

Acknowledgement. I thank Remco van der Hofstad for drawing my attention to continuous time branching processes as a possible tool for analyzing preferential attachment models with vertex death, and Gerard Hooghiemstra for pointing me to Lemma 5.4 in van der Hofstad et al. (2000).

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