

of simple Lie algebra  $\mathfrak{g}$  there are several deformations; the number of parameters in the last example is equal to the rank of  $\mathfrak{g}$  and leads to generalizations of the **Lie algebras** of “matrices of complex size”, cf. [5]. The Poisson superalgebra on the vector **superspace** can be realized by vector fields  $D$  as

$$\{D \mid L_D(\alpha_1) = 0\},$$

$$\alpha_1 = dt - \sum (p_i dq_i - q_i dp_i) - \sum \varepsilon_j \theta_j d\theta_j.$$

Similarly, the *Buttin superalgebra* (with *Schouten bracket*, i.e., **antibracket**) is

$$\{D \mid L_D(\alpha_0) = 0\}, \quad \alpha = d\tau - \sum (\theta_i dq_i + q_i d\theta_i).$$

The *deformed Buttin superalgebra* is

$$\mathfrak{b}_{a,b}(n) = \{D \in \mathfrak{vect}(n|n+1) \mid L_D(\alpha_{q,\xi,\tau}^{a-bn}) = 0\}.$$

Instead of  $a, b$ , one can consider one parameter

$$\lambda = \frac{2a}{n(a-b)} \in P^1.$$

The *structure functions* (obstructions to flattening the corresponding  $G$ -structure) are computed in [3]. For infinite dimensional analogs see [4].

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*Dimitry Leites*

**SUPERTIME** — A **supermanifold** of values of a dynamical parameter. On manifolds, Time is usually 1-dimensional, a different example is *Kadomtsev–Petviashvili hierarchy* in which an infinite dimensional manifold is interpreted as Time.

On finite dimensional manifolds, Time is always 1-dimensional as follows from the *rectifiability* of vector field theorem studied at early courses of differential equations. Shander generalized the theorem on *rectifiability* of vector fields to nondegenerate fields on **supermanifolds** and gave the following characterization of

such fields, in particular, the ones used in SUSY theories: the nondegenerate (at a point) vector field  $X$  can locally be reduced to the form  $D_0 = \frac{\partial}{\partial x}$ , where  $x$  is an even coordinate, if  $X$  is even, to the form  $D_1 = \frac{\partial}{\partial \theta}$ , where  $\theta$  is an odd coordinate, if  $X$  is odd and  $X^2 = 0$ , or to the form  $D = \frac{\partial}{\partial \theta} + \theta \frac{\partial}{\partial x}$ , if  $X$  is odd and  $X^2 \neq 0$ .

Shander explained that for dynamical systems on **supermanifolds** **supertime** runs a (1|1)-dimensional **supermanifold** with parameters  $t, \tau$ . Shander gave examples with **Poisson bracket** and **antibracket**, e.g., he showed that the most profound dynamics is given not by  $D_0(f) = \{f, H\}$ , but by

$$D(f) = \{f, H\},$$

where the parity of the Hamiltonian,  $H$ , should be opposite to that of the (anti)bracket  $\{\cdot, \cdot\}$ , indeed

$$D_0(f) = \frac{1}{2} \{f, \{H, H\}\}.$$

This explanation enables one to pick up odd parameters missed under the conventional crude approach, but no physical paper used this so far.

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*Dimitry Leites*

**SUPERTRACE** — A linear functional on a **Lie superalgebra** that vanishes on the superbracket and denoted by str (or just tr). For the definition of the “usual” **supertrace** of the *supermatrix*, not necessarily in the standard format, see [1,2]. There is also *queertrace*, qtr, defined on a “queer” superanalog of the matrix algebra  $\mathfrak{q}(n)$  by the same characteristic property but since  $\mathfrak{q}(n)$  is a subalgebra in  $\mathfrak{gl}(n|n)$  we can compare str and qtr and see that they are totally different functions; in particular, one is even and the other one is odd, [3]. Both **supertrace** and *queertrace* have a contraction into the **Berezin integral** — the **supertrace** on the *Poisson–Lie superalgebra*  $\mathfrak{po}(0|n)$  whose parity is equal to that of  $n$ .

These **supertraces**, being defined on finite dimensional algebras, can be integrated to groups, so they correspond to **superdeterminants**:

$$\det(\exp(X)) = e^{\text{tr}(X)}.$$

There are also superanalogues of trace on infinite dimensional **Lie superalgebras**, they do not necessarily correspond to **superdeterminants**. Examples: *stringy* superalgebras  $\mathfrak{t}^L(1|4)$  and  $\mathfrak{t}^M(1|5)$ , cf. [4], *special Buttin superalgebras*  $\mathfrak{sb}(n)$ , and divergence free algebras  $\mathfrak{svect}(1|n)$ . The parity of these **supertraces** is equal to that of the number of odd indeterminates.

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*Dimitry Leites*

**SUPERTRACE FORMULA** — A linear form  $\phi$  on a  $\mathbb{Z}_2$ -graded (super)algebra  $A$  satisfying  $\phi([a, b]) = 0$  for all  $a, b \in A$ , where  $[a, b]$  is the **supercommutator** (see entry). When  $V = V^+ \oplus V^-$  is a  $\mathbb{Z}_2$ -graded vector space, the endomorphism algebra  $\text{End}(V)$  provides an example of a superalgebra for which there exists a canonical **supertrace** given by

$$\text{Str}(a) = \begin{cases} \text{tr}_+(a) - \text{tr}_-(a), & \text{if } |a|=0; \\ \text{tr}_+(a) + \text{tr}_-(a), & \text{if } |a|=1, \end{cases}$$

where  $\text{tr}_\pm$  is the ordinary trace on  $\text{End}(V^\pm)$ , and  $a \in \text{End}(V)$  is said to have degree  $|a| = 0$  (resp. 1) if it maps  $V^\pm$  into  $V^\pm$  (resp.  $V^\mp$ ). Observe that the **supertrace** of the odd matrix is given by the usual trace.

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*Gert Roepstorff*

**SUPERTUBE** — A stable supersymmetric configurations of cylindrical topology for D2-branes in *type IIA string theory* preserving a quarter of the supersymmetries of the flat *Minkowski spacetime* [1]. The supertubes are supported against collapse by an angular momentum, which is the result of a combined electric and magnetic field on the world volume. They can be obtained by starting from a sequence of *D0-branes* placed on a long string, like beads on a necklace. This structure then starts spinning around the longitudinal axis and blows up into a supertube [1,2].

The generalizations of the supertube in a T-dual *type IIB* picture, when the **T-duality** acts along a perpendicular direction and along the supertube were studied in [2] and [3]. The supertubes in the matrix model context were considered in [4]. A direct generalization of supertubes, when the string networks (or **web** [5]) indeed blow up into D3-branes, is called D3-supertube [6] or supersheet [7].

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*Steven Duplij*

**SUPERTWISTOR** — A space  $\mathcal{Y}_A = (\lambda_\alpha, \mu^\alpha, \chi)$ , where  $\lambda_\alpha, \mu^\alpha$  are real commuting **spinors** and  $\chi$  is a real anti-commuting **spinor**,  $\alpha = 1, \dots, 2^k$  and  $2^k$  is equal to the dimension of an irreducible **spinor** representation of  $SO(1, D-1)$  in  $D = 3, 4, 6, 10 \pmod{8}$  [1]. The generalized Penrose–Ferber correspondence between real **supertwistors** and real generalized **superspace**  $(X^{\alpha\beta}, \Theta^\alpha)$  is [2]

$$\begin{aligned} \mu^\alpha &= X^{\alpha\beta} \lambda_\beta - i \Theta^\alpha (\Theta^\beta \lambda_\beta), \\ \zeta &= \Theta^\alpha \lambda_\alpha. \end{aligned}$$

The generalization of the Cartan–Penrose representation is  $P_{\alpha\beta} = \lambda_\alpha \lambda_\beta$  solving the BPS condition  $\det P_{\alpha\beta} = 0$  [3].

The relativistic superparticle is a constrained dynamical system not all its dynamical variables are independent, and so by performing **supertwistor** transform one deals directly with independent physical degrees of freedom of the superparticle in a covariant way, which simplifies the quantization procedure and the analysis of the spectrum of quantum states of the model [1].

For **supertwistor** applications in various superparticle models [3–5].

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*Steven Duplij*

**SUPERVECTOR BUNDLES, general ground rings formulation** — A well-behaved theory of supervector bundles within the general **category** of **supermanifolds** is described in [3] and a more detailed treatment in [1].

Let  $\mathfrak{X} = (X, \mathcal{A}, ev^X)$ ,  $\mathfrak{Y} = (Y, \mathcal{B}, ev^Y)$  be two **supermanifolds** based on a ground *graded Banach algebra*  $\Lambda$  satisfying appropriate (but quite loose) conditions, cf. [3]. The *product supermanifold*  $\mathfrak{Z} = (Z, \mathcal{C}, ev^Z)$  is constructed by taking  $Z = X \times Y$  as topological spaces while the *structure sheaf*  $\mathcal{D}$  is the **sheaf** associated to